

# Higher Moment Varieties of Non-Gaussian Graphical Models

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## Abstract

We study non-Gaussian graphical models from a perspective of algebraic statistics. Our focus is on algebraic relations among second and third moments in graphical models given by linear structural equations. We show that when the graph is a tree these relations form a toric ideal. Furthermore, from the covariance matrix and the third moment tensor, we construct explicit matrices whose  $2 \times 2$  minors define the model set-theoretically. The matrices are associated to treks and multi-treks in the path, and computational experiments support our conjecture that their minors also generate the vanishing ideal of the model. We use the computer algebra software `Macaulay2` to compute concrete examples and describe the ideals for models with hidden variables.

## 1 Introduction

In this paper we study algebraic-geometric aspects of directed graphical models, which are a class of statistical models that hypothesize noisy functional (or in other words, cause-effect) relations among a set of random variables [3]. The models are graphical in the sense of using a graph to encode in an intuitive manner which variables appear in each functional relation, as we detail below. For a number of statistical tasks, including model selection, it has proven very useful to have insights about algebraic structure in characteristics of the joint distribution [1]. One prominent example are results on algebraic relations among second moments, i.e., covariances, in models that postulate linear functional relationships among the variables; see e.g. [2, 7].

In contrast to earlier work in algebraic statistics, we conduct here a first systematic study on algebraic relations that also involve higher moments, specifically we focus on second and third moments. Higher moments are of crucial importance for the case of non-Gaussian models, where different models may have identical structure in second but not in all higher moments [5, 6]. For instance, a particular type of algebraic relations among second and third moments was used in [8] to design a model selection method suitable for high-dimensional data.

We begin by reviewing the models of interest. Let  $G = (V, E)$  be a directed acyclic graph (DAG), and let  $X_i$ ,  $i \in V$ , be a collection of random variables indexed by the vertices in  $V$ . A vertex  $j \in V$  is a parent of vertex  $i$  if there is an edge pointing from  $j$  to  $i$ , i.e., if  $(j, i) \in E$ . We denote the set of all parents of  $i$  by  $\text{pa}(i)$ . The graph  $G$  gives rise to the linear structural equation model that postulates that

$$X_i = \sum_{j \in \text{pa}(i)} \lambda_{j,i} X_j + \varepsilon_i, \quad i \in V.$$

where  $\varepsilon_i$  are mutually independent random variables that represent stochastic errors and have expectation  $\mathbb{E}[\varepsilon_i] = 0$ . The coefficients  $\lambda_{j,i}$  are unknown parameters, and we fill them into a matrix  $\Lambda = (\lambda_{j,i})$  by adding a zero entry when  $(j, i) \notin E$ . We denote the set of all such matrices as  $\mathbb{R}^E$ . We note that for simplicity, and without loss of generality, the above equations do not include a constant term, so  $\mathbb{E}[X_i] = 0$  for all  $i$ .

**Definition 1.1.** The linear structural equation model  $\mathcal{M}^{(2,3)}(G)$  of second and third order moments corresponding to a directed acyclic graph  $G = (V, E)$  with  $|V| = n$  is defined as

$$\begin{aligned} \mathcal{M}^{(2,3)}(G) = \{ & (S = (I - \Lambda)^{-T} \Omega^{(2)} (I - \Lambda)^{-1}, \\ & T = \Omega^{(3)} \bullet (I - \Lambda)^{-1} \bullet (I - \Lambda)^{-1} \bullet (I - \Lambda)^{-1}) : \\ & \Omega^{(2)} \text{ is } n \times n \text{ positive definite diagonal matrix,} \\ & \Omega^{(3)} \text{ is } n \times n \times n \text{ diagonal 3-way tensor, and } \Lambda \in \mathbb{R}^E \}. \end{aligned}$$

Here,  $\bullet$  denotes the Tucker product, see [4, Lemma 1]. Furthermore, denote by  $\mathcal{I}^{(2,3)}(G)$  the ideal of polynomials in the entries  $s_{ij}$  of  $S$  and  $t_{ijk}$  of  $T$  that vanish on the model  $\mathcal{M}^{(2,3)}(G)$ .

## 2 Parametrization

We always work over DAGs  $G$  with the edges topologically ordered so that if  $i \rightarrow j \in E(G)$ , then  $i < j$ .

**Definition 2.1.** A trek (or 2-trek)  $\tau$  from  $i$  to  $j$  is an alternating sequence of nodes and edges of the form

$$i \leftarrow i_l \leftarrow \cdots \leftarrow i_1 \longleftarrow i_0 \longrightarrow j_1 \rightarrow \cdots \rightarrow j_r \rightarrow j.$$

(a trek takes you up and down a ‘mountain’). The top of the trek is  $\text{top}(\tau) = i_0$ . We can generalize this notion to a  $n$ -trek between  $n$  vertices  $i_1, \dots, i_n$ , as an ordered collection of  $n$  directed paths  $T = (P_1, \dots, P_n)$  where  $P_r$  has sink  $i_r$  and they all share the same top vertex as source,  $\text{top}(T)$ .

Define  $T(i_1, \dots, i_n)$  to be the collection of minimal –in the sense that it does not factor through another  $n$ -trek in the set–  $n$ -treks between  $i_1, \dots, i_n$ . Consider the ring morphism

$$\begin{aligned} \phi_G : \mathbb{C}[s_{ij}, t_{ijk} \mid 1 \leq i \leq j \leq k \leq n] & \rightarrow \mathbb{C}[a_i, b_i, \lambda_{ij} \mid i \rightarrow j \in E(G)] \\ s_{ij} & \mapsto \sum_{T \in T(i,j)} a_{\text{top}(T)} \prod_{k \rightarrow l \in T} \lambda_{kl}, \\ t_{ijk} & \mapsto \sum_{T \in T(i,j,k)} b_{\text{top}(T)} \prod_{m \rightarrow l \in T} \lambda_{ml}. \end{aligned}$$

**Proposition 2.2.** [Simple trek rule parametrization] Let  $G = (V, E)$  be a DAG and  $\phi_G$  the ring morphism defined above. Then  $\mathcal{I}^{(2,3)}(G) = \ker \phi_G$ .

*Proof.* One can generalize the analogous construction for the variables  $s_{i,j}$  that can be found in [7, Proposition 2.3].  $\square$

For trees, the shortest  $n$ -trek between  $i_1, \dots, i_n$ , if it exists, is unique. Therefore the notion of top is well-defined just by setting the end vertices, that is,  $\text{top}(i_1, \dots, i_n)$  is the largest  $t$  such that the corresponding vertex is the top of the shortest  $n$ -trek between  $i_1, \dots, i_n$ .

**Corollary 2.3.** If  $G$  is a tree,  $\mathcal{I}^{(2,3)}(G)$  is a toric ideal.

*Proof.* For trees, the set of minimal treks  $T(i_1, \dots, i_n)$  has at most one element: the unique shortest  $n$ -trek, if it exists. Therefore, the image of  $\phi_G$  is generated by monomials.  $\square$

### 3 Tree DAGs

In this section we find equations defining the model  $\mathcal{M}^{(2,3)}(G)$  whenever  $G$  is a tree, i.e., its underlying undirected graph is a tree. In this case, the model has a monomial parametrization, and we show that it is cut out by quadratic binomials.

**Definition 3.1.** Let  $i, j \in V$  be two vertices such that a 2-trek between  $i$  and  $j$  exists. We define the matrix

$$A_{i,j} := \begin{bmatrix} s_{ik_1} & \cdots & s_{ik_r} & t_{i\ell_1 m_1} & \cdots & t_{i\ell_q m_q} \\ s_{jk_1} & \cdots & s_{jk_r} & t_{j\ell_1 m_1} & \cdots & t_{j\ell_q m_q} \end{bmatrix},$$

where

- $k_1, \dots, k_r$  are all vertices such that  $\text{top}(i, k_a) = \text{top}(j, k_a)$  and
- $(\ell_1, m_1), \dots, (\ell_q, m_q)$  are all pairs of vertices such that  $\text{top}(i, \ell_b, m_b) = \text{top}(j, \ell_b, m_b)$ .

**Theorem 3.2.** Let  $G = (V, E)$  be a tree DAG. For all  $i, j \in V$  such that there is no trek between  $i$  and  $j$ , and for all  $i, j, k \in V$  such that there is no 3-trek between  $i, j$  and  $k$ , we have that  $s_{ij}, t_{ijk} \in \mathcal{I}^{(2,3)}(G)$ . For all  $i, j \in V$  such that there is a 2-trek between  $i$  and  $j$ , the  $2 \times 2$  subdeterminants of  $A_{ij}$  lie in  $\mathcal{I}^{(2,3)}(G)$ .

*Proof.* For all  $i, j \in V$  such that there is no trek between them, by the trek rule,  $s_{ij} = 0$ . Similarly, by the 3-trek-rule, if there is no 3-trek between  $i, j, k$ , then  $t_{ijk} = 0$ .

Consider a matrix  $A_{i,j}$  as in Definition 3.1. Fix any two columns of the matrix with indexes  $k$  ( $s$  columns) and  $l, m$  ( $t$  columns). Set  $a := \text{top}(i, k) = \text{top}(j, k)$  and  $b := \text{top}(i, l, m) = \text{top}(j, l, m)$ .

The 2-treks between  $i$  and  $j$  with tops  $a$  and  $b$ , respectively, factor through the shortest 2-trek with top  $\text{top}(i, j)$ . Moreover, there is exactly one path between two nodes of a tree, hence both the 2-treks (encoded in  $s_{i,k}$  and  $s_{j,k}$ ) and 3-treks (encoded in  $t_{ilm}$  and  $t_{jlm}$ ) factor through  $\text{top}(i, j)$  as follows:

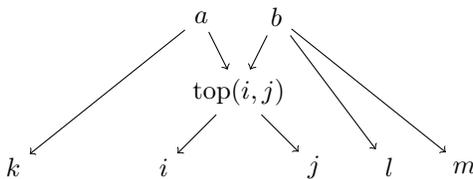


Figure 1: Factorization of 2-treks between  $i$  and  $j$  with tops  $a$  and  $b$  through unique shortest 2-trek.

From Figure 1 and Proposition 2.2, it follows that  $s_{ik}t_{jlm} - s_{jk}t_{ilm}$  belongs to  $\ker \phi_G$ .

Cases corresponding to two  $s$  columns or two  $t$  columns are dealt analogously, since only central part of Figure 1 matters.  $\square$

**Remark 3.3.** Note that  $\text{top}(i, j)$  is a *choke point* between  $I = \{k, i\}$  and  $J = \{j, l, m\}$  as defined in [7].

For the covariance case, all quadratic binomials arise from 2-minors of  $A_{ij}$  as in [7, Tetrad representation]. However this is no longer the case for third moments or combinations of covariance and moments:

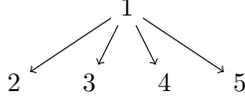


Figure 2: Not all quadratic binomials arise from 2-minors of  $A_{i,j}$ .

**Example 3.4.** In the graph below  $f = s_{2,3}t_{1,4,5} - s_{4,5}t_{1,2,3} \in I_G$  and because of the lack of repeated indices in  $s$ , this cannot come from a 2-minor of  $A_{i,j}$ . However, this binomial is not necessary in order to generate the vanishing ideal of the model. Indeed,

$$f = (s_{2,3}t_{1,4,5} - s_{3,4}t_{1,2,5}) + (s_{3,4}t_{1,2,5} - s_{4,5}t_{1,2,3})$$

is the sum of 2-minors of  $A_{2,4}$  and  $A_{3,5}$ , respectively.

**Proposition 3.5.** *All quadratic binomials in  $\mathcal{I}^{(2,3)}(G)$  are linear combinations of 2-minors of matrices  $A_{i,j}$ .*

*Proof.* Let  $f = m_1 + m_2 \in I_G$  be a quadratic binomial. By 2.2, the tops of the underlying 2- or 3-treks of  $m_1$  must be pairwise equal to the tops associated to  $m_2$ . Moreover, the indices of the variables in  $m_2$  must be a permutation of the indices of  $m_1$ .

If  $f$  is a quadratic binomial on variables  $t$ , then  $f = t_{i,j,k}t_{l,m,n} - t_{\sigma(i),\sigma(j),\sigma(k)}t_{\sigma(l),\sigma(m),\sigma(n)}$ , where the  $\{i, j, k\} \cup \{\sigma(i), \sigma(j), \sigma(k)\}$  has either one or two elements.

If the intersection consists of a single element, then we can assume  $f = t_{i,j,k}t_{l,m,n} - t_{i,l,m}t_{j,k,n}$ . If  $\text{top}(i, j, k) = \text{top}(j, k, n)$  and  $\text{top}(i, l, m) = \text{top}(l, m, n)$ , then

$$\begin{array}{c|cc} & (j, k) & (l, m) \\ \hline i & t_{ijk} & t_{ilm} \\ n & t_{jkn} & t_{lmn} \end{array} \quad (1)$$

is a 2-minor of  $A_{i,n}$ . Otherwise, we need to exchange the elements in the skew-diagonal in order to have equal tops  $b_1 := \text{top}(i, j, k) = \text{top}(i, l, m)$  and  $b_2 := \text{top}(j, k, n) = \text{top}(l, m, n)$  arranged in columns. The resulting matrix

$$\begin{array}{c|cc} & i & n \\ \hline (j, k) & t_{ijk} & t_{jkn} \\ (l, m) & t_{ilm} & t_{lmn} \end{array} \quad (2)$$

has not the desired shape. Consider the two 4-treks between  $j, k, l$  and  $m$ , one with top  $b_1$  and the other with top  $b_2$ . Because  $G$  is a tree, one must factor through the other. Assume  $b_1 \leq b_2$ , then the determinant of (2) can be written as the sum of the determinants of the corresponding 2-minors in  $A_{k,l}$  and  $A_{j,m}$ .

If the intersection consists of two elements, we can proceed analogously.

If  $f$  is a quadratic binomial on both variables  $s$  and  $t$ , it can be proved that either  $f$  arises as a 2-minor of a matrix in 3.1 or it is a sum of two such matrices.  $\square$

**Remark 3.6.** In (2) of the proof above, we see that  $t_{i,j,k}t_{l,m,n} - t_{i,l,m}t_{j,k,n}$  is the sum of the determinants of

$$\begin{array}{c|cc} A_{k,l} & (i, j) & (m, n) \\ \hline k & t_{ijk} & t_{kmn} \\ l & t_{ijl} & t_{lmn} \end{array} \quad \text{and} \quad \begin{array}{c|cc} A_{j,m} & (i, l) & (k, n) \\ \hline j & t_{ijl} & t_{jkn} \\ m & t_{ilm} & t_{kmn} \end{array}. \quad (3)$$

The indices in  $A_{k,l}$  and  $A_{j,m}$  indicate which paths in the 3-trek we exchange between the two terms of the determinant, as represented in Figure 3.

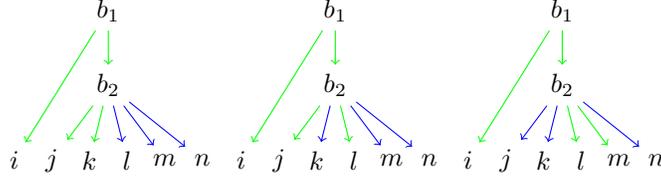


Figure 3: From left to right: pairs of 3-treks representing terms  $t_{ijk}t_{lmn}$ ,  $t_{ijl}t_{kmn}$ ,  $t_{ilm}t_{jkn}$ . First two pictures correspond to the determinant of the 2-minor of  $A_{kl}$  displayed in (3) and last two correspond to  $A_{jm}$ .

Let  $I$  be the ideal generated by matrices  $A_{i,j}$  in Definition 3.1 and linear generators  $s_{ij}$  and  $t_{ijk}$  when there is no 2-trek between  $i, j$  or no 3-trek between  $i, j, k$ .

**Conjecture 3.7.** *All binomials in  $\mathcal{I}^{(2,3)}(G)$  are generated by quadratic binomials, that is  $\mathcal{I}^{(2,3)}(G) = I$ .*

Although the equality of the ideals  $\mathcal{I}^{(2,3)}(G)$  and  $I$  is yet to be proved, the next result shows that the model  $\mathcal{M}^{(2,3)}(G)$  is the variety  $V(I)$  intersected with the cone of positive definite matrices  $PD(n)$ . In fact, it is not necessary to consider all quadratic binomials arising from matrices  $A_{i,j}$  in order to prove this set-theoretical equality.

**Theorem 3.8.** *Let  $J$  be the ideal generated by the linear generators of  $I$  but only matrices  $A_{i,j}$  such that there is a directed path between  $i$  and  $j$ . Then the model  $\mathcal{M}^{(2,3)}(G)$  is the variety  $V(J)$  intersected with the cone  $PD(n)$ .*

*Proof.* Let  $S$  and  $T$  be the second and third moments of a distribution such that  $(S, T) \in \mathcal{M}^{(2,3)}(G)$ . For any edge  $i \rightarrow j \in E$ , consider the matrix  $A_{i,j}$ . Note that it contains as a column the vector  $[s_{ii}, s_{ij}]^T$ . Let  $\lambda_{ij} = \frac{s_{ij}}{s_{ii}}$ , and let  $\Lambda \in \mathbb{R}^E$  contain these as its entries. Consider

$$S' = (I - \Lambda)^T S (I - \Lambda), \quad T' = T \bullet (I - \Lambda) \bullet (I - \Lambda) \bullet (I - \Lambda).$$

We will now show that  $S'$  and  $T'$  are diagonal. For any  $i \neq j$ , we have that

$$\begin{aligned} s'_{ij} &= \sum_{k, \ell} (I - \Lambda)_{ki} s_{k\ell} (I - \Lambda)_{\ell j} \\ &= s_{ij} - \sum_{k \rightarrow i \in E} \lambda_{ki} s_{kj} - \sum_{\ell \rightarrow j \in E} \lambda_{l j} s_{i\ell} + \sum_{k \rightarrow i, \ell \rightarrow j \in E} \lambda_{ki} \lambda_{l j} s_{k\ell}. \end{aligned}$$

We are going to consider 3 cases.

**Case 1:** The shortest path between  $i$  and  $j$  has a collider. In this case,  $s_{ij} = 0$ . Furthermore, for any  $k \rightarrow i$ , the shortest path between  $k$  and  $j$  also has a collider: it either goes through  $i$ ; or  $k$  is on the shortest path between  $i$  and  $j$ , but since  $k$  cannot be a collider, then, the shortest path between  $k$  and  $j$  has a collider. Thus,  $s_{kj} = 0$ , and the first sum is 0. Similarly, the other two sums are also 0. Therefore,  $s'_{ij} = 0$ .

**Case 2:** The shortest path between  $i$  and  $j$  is a trek of the form  $i \leftarrow i_0 \cdots j_0 \rightarrow j$ . Then, in the sums  $\sum_{k \rightarrow i \in E} \lambda_{ki} s_{kj}$ ,  $\sum_{\ell \rightarrow j \in E} \lambda_{l j} s_{i\ell}$ , and  $\sum_{k \rightarrow i, \ell \rightarrow j \in E} \lambda_{ki} \lambda_{l j} s_{k\ell}$  the only nonzero terms appear when  $k = i_0$  and  $\ell = j_0$  (otherwise, for example, the shortest path between  $k$  and  $j$  has a collider, namely,  $i$ , so  $s_{kj} = 0$ ). When  $k = i_0$  and  $\ell = j_0$ ,  $\lambda_{ki} = \frac{s_{ki}}{s_{ki}} = \frac{s_{ij}}{s_{kj}}$  since  $\text{top}(i, j) = \text{top}(k, j)$ , therefore,  $(s_{ik}, s_{kk})^T, (s_{ij}, s_{kj})^T$  are columns in the matrix  $A_{i,k}$ . Similarly,  $(s_{ji}, s_{li})^T, (s_{jk}, s_{lk})^T, (s_{lj}, s_{ll})^T$  are columns in the matrix  $A_{\ell, j}$  therefore,  $\lambda_{l j} = \frac{s_{ij}}{s_{il}} = \frac{s_{kj}}{s_{kl}}$ . Therefore,

$$s'_{ij} = s_{ij} - \frac{s_{ij}}{s_{kj}} s_{kj} - \frac{s_{ij}}{s_{il}} s_{il} + \frac{s_{ij}}{s_{kj}} \frac{s_{kj}}{s_{kl}} s_{kl} = 0.$$

Note that either  $s_{kj} \neq 0$  or both  $s_{kj} = s_{ij} = 0$ , hence  $s'_{ij}$  is either way well-defined. This situation is often repeated along the rest of the proof.

Case 3: The shortest path between  $i$  and  $j$  is a trek of the form:  $i \rightarrow \cdots \rightarrow j_0 \rightarrow j$  or  $i \leftarrow i_0 \cdots \leftarrow j$ . WLOG, consider the former case. Then, the sums  $\sum_{\ell \rightarrow j \in E} \lambda_{lj} s_{i\ell}$  and  $\sum_{k \rightarrow i, \ell \rightarrow j \in E} \lambda_{ki} \lambda_{\ell j} s_{k\ell}$  are nonzero only when  $\ell = j_0$  (otherwise,  $s_{i\ell}$  and  $s_{k\ell}$  are 0 because  $j$  is a collider on the shortest path between  $i$  and  $\ell$  and the one between  $j$  and  $\ell$ ). Thus, we have that

$$s'_{ij} = s_{ij} - \sum_{k \in \text{pa}(i)} \lambda_{ki} s_{kj} - \lambda_{j_0 j} s_{ij_0} + \sum_{k \in \text{pa}(i)} \lambda_{ki} \lambda_{j_0 j} s_{kj_0}.$$

Note that  $(s_{ji}, s_{j_0 i})^T, (s_{jj_0}, s_{j_0 j_0})^T$  are both columns in the matrix  $A_{j, j_0}$ , since  $\text{top}(i, j_0) = \text{top}(i, j) = i$ . Thus,

$$s'_{ij} = s_{ij} - \frac{s_{ij}}{s_{ij_0}} s_{ij_0} + \sum_{k \in \text{pa}(i)} \lambda_{ki} (\lambda_{j_0 j} s_{kj_0} - s_{kj}).$$

Furthermore, since  $(s_{kj}, s_{kj_0})^T, (s_{j_0 j}, s_{j_0 j_0})^T$  are columns in  $A_{j_0, j}$ , then

$$= \sum_{k \in \text{pa}(i)} \lambda_{ki} \begin{pmatrix} s_{kj} \\ s_{kj_0} \end{pmatrix} (s_{kj_0} - s_{kj}) = 0.$$

Therefore,  $S'$  is diagonal.

We now proceed to showing that  $T'$  is diagonal. Note that, because,  $G$  is a tree DAG, for any three vertices  $i, j, k$  for which there is a 3-trek between them, there is a unique shortest 3-trek. We have that

$$\begin{aligned} t'_{ijk} &= \sum_{a, b, c} (I - \Lambda)_{ai} (I - \Lambda)_{bj} (I - \Lambda)_{ck} t_{abc} \\ &= t_{ijk} - \sum_{a \rightarrow i \in E} \lambda_{ai} t_{ajk} - \sum_{b \rightarrow j \in E} \lambda_{bj} t_{ibk} - \sum_{c \rightarrow k \in E} \lambda_{ck} t_{ijc} + \sum_{a \rightarrow i, b \rightarrow j \in E} \lambda_{ai} \lambda_{bj} t_{abk} \\ &\quad + \sum_{a \rightarrow i, c \rightarrow k \in E} \lambda_{ai} \lambda_{ck} t_{ajc} + \sum_{b \rightarrow j, c \rightarrow k \in E} \lambda_{bj} \lambda_{ck} t_{ibc} - \sum_{a \rightarrow i, b \rightarrow j, c \rightarrow k \in E} \lambda_{ai} \lambda_{bj} \lambda_{ck} t_{abc} \end{aligned}$$

Case 1: There is no 3-trek between  $i, j, k$ , i.e.,  $t_{ijk} = 0$ . Then, all of the 7 sums in the above expression will also be 0. This is because if there is a 3-trek between  $a, b, c$  such that  $a = i$  or  $a \rightarrow i$ , and the same for  $b, j$  and  $c, k$ , then, we can complete this 3-trek to a 3-trek between  $i, j, k$ . Therefore, if there is no 3-trek between  $i, j, k$ , then,  $t'_{ijk} = 0$ .

Case 2: There is a 3-trek between  $i, j, k$ . Thus,  $i, j, k$  have a unique common closest ancestor, call it  $v$ .

Case 2.0: Suppose first that  $v \neq i, j, k$ . Therefore, the shortest 3-trek between  $i, j, k$  consists of 3 nontrivial directed paths  $v \rightarrow \cdots \rightarrow i_0 \rightarrow i, v \rightarrow \cdots \rightarrow j_0 \rightarrow j$ , and  $v \rightarrow \cdots \rightarrow k_0 \rightarrow k$ . Because  $G$  is a tree DAG, the seven sums above can be nonzero if and only if  $a = i_0, b = j_0, c = k_0$  (otherwise, there cannot be a 3-trek between  $a, b$ , and  $c$ ). Thus,

$$\begin{aligned} t'_{ijk} &= t_{ijk} - \lambda_{i_0 i} t_{i_0 jk} - \lambda_{j_0 j} t_{ij_0 k} - \lambda_{k_0 k} t_{ij k_0} + \lambda_{i_0 i} \lambda_{j_0 j} t_{i_0 j_0 k} \\ &\quad + \lambda_{i_0 i} \lambda_{k_0 k} t_{i_0 j k_0} + \lambda_{j_0 j} \lambda_{k_0 k} t_{ij_0 k_0} - \lambda_{i_0 i} \lambda_{j_0 j} \lambda_{k_0 k} t_{i_0 j_0 k_0}. \end{aligned}$$

Since  $(S, T) \in \mathcal{V}(I)$ , we have that, for example,  $(s_{i_0 i}, s_{i_0 i_0})^T, (t_{ijk}, t_{i_0 jk})^T$  are both columns in  $A_{i, i_0}$ , and, therefore,  $\lambda_{i_0 i} = \frac{t_{ijk}}{t_{i_0 jk}}$  (and similarly for the other  $\lambda$ 's in the expression above). Thus,

$$\begin{aligned} t'_{ijk} &= t_{ijk} - \frac{t_{ijk}}{t_{i_0 jk}} t_{i_0 jk} - \frac{t_{ijk}}{t_{ij_0 k}} t_{ij_0 k} - \frac{t_{ijk}}{t_{ij k_0}} t_{ij k_0} + \frac{t_{ij_0 k}}{t_{i_0 j_0 k}} \frac{t_{ijk}}{t_{ij_0 k}} t_{i_0 j_0 k} \\ &\quad + \frac{t_{ij_0 k_0}}{t_{i_0 j_0 k_0}} \frac{t_{ijk}}{t_{ij_0 k_0}} t_{i_0 j_0 k_0} + \frac{t_{ij k_0}}{t_{ij_0 k_0}} \frac{t_{ijk}}{t_{ij_0 k_0}} t_{ij_0 k_0} - \frac{t_{ijk}}{t_{i_0 jk}} \frac{t_{i_0 jk}}{t_{i_0 j_0 k}} \frac{t_{i_0 j_0 k}}{t_{i_0 j_0 k_0}} t_{i_0 j_0 k_0} = 0. \end{aligned}$$

Case 2.1:  $v = i \neq j, k$ . In this case, the shortest 3-trek between  $i, j, k$  consists of the trivial path  $i$  and paths  $i \rightarrow \dots \rightarrow j_0 \rightarrow j$ , and  $i \rightarrow \dots \rightarrow k_0 \rightarrow k$ . Therefore, we have that

$$\begin{aligned}
t'_{ijk} &= t_{ijk} - \sum_{a \in \text{pa}(i)} \lambda_{ai} t_{ajk} - \lambda_{j_0 j} t_{ij_0 k} - \lambda_{k_0 k} t_{ijk_0} + \sum_{a \in \text{pa}(i)} \lambda_{ai} \lambda_{j_0 j} t_{aj_0 k} \\
&\quad + \sum_{a \in \text{pa}(i)} \lambda_{ai} \lambda_{k_0 k} t_{ajk_0} + \lambda_{j_0 j} \lambda_{k_0 k} t_{ij_0 k_0} - \sum_{a \in \text{pa}(i)} \lambda_{ai} \lambda_{j_0 j} \lambda_{k_0 k} t_{aj_0 k_0} \\
&= t_{ijk} - \sum_{a \in \text{pa}(i)} \lambda_{ai} t_{ajk} - \frac{t_{ijk}}{t_{ij_0 k}} t_{ij_0 k} - \frac{t_{ijk}}{t_{ijk_0}} t_{ijk_0} + \sum_{a \in \text{pa}(i)} \lambda_{ai} \frac{t_{ajk}}{t_{aj_0 k}} t_{aj_0 k} \\
&\quad + \sum_{a \in \text{pa}(i)} \lambda_{ai} \frac{t_{ajk}}{t_{ajk_0}} t_{ajk_0} + \frac{t_{ijk}}{t_{ij_0 k}} \frac{t_{ij_0 k}}{t_{ij_0 k_0}} t_{ij_0 k_0} - \sum_{a \in \text{pa}(i)} \lambda_{ai} \frac{t_{ajk}}{t_{aj_0 k}} \frac{t_{aj_0 k}}{t_{aj_0 k_0}} t_{aj_0 k_0} = 0.
\end{aligned}$$

Case 2.2:  $v = i = j \neq k$ . In this case, the shortest 3-trek between  $i, j, k$  consists of the two trivial paths  $i$  and  $j$ , and  $i \rightarrow \dots \rightarrow k_0 \rightarrow k$ . Therefore, we have that

$$\begin{aligned}
t'_{iik} &= t_{iik} - \sum_{a \in \text{pa}(i)} \lambda_{ai} t_{aik} - \sum_{a \in \text{pa}(i)} \lambda_{ai} t_{iak} - \lambda_{k_0 k} t_{iik_0} + \sum_{a \in \text{pa}(i)} \lambda_{ai}^2 t_{aak} \\
&\quad + \sum_{a \in \text{pa}(i)} \lambda_{ai} \lambda_{k_0 k} t_{aik_0} + \sum_{a \in \text{pa}(i)} \lambda_{ai} \lambda_{k_0 k} t_{iak_0} - \sum_{a \in \text{pa}(i)} \lambda_{ai}^2 \lambda_{k_0 k} t_{aak_0} \\
&= t_{iik} - \sum_{a \in \text{pa}(i)} \lambda_{ai} t_{aik} - \sum_{a \in \text{pa}(i)} \lambda_{ai} t_{iak} - \frac{t_{iik}}{t_{iik_0}} t_{iik_0} + \sum_{a \in \text{pa}(i)} \lambda_{ai}^2 t_{aak} \\
&\quad + \sum_{a \in \text{pa}(i)} \lambda_{ai} \frac{t_{aik}}{t_{aik_0}} t_{aik_0} + \sum_{a \in \text{pa}(i)} \lambda_{ai} \frac{t_{iak}}{t_{iak_0}} t_{iak_0} - \sum_{a \in \text{pa}(i)} \lambda_{ai}^2 \frac{t_{aak}}{t_{aak_0}} t_{aak_0} = 0.
\end{aligned}$$

Therefore, in all cases,  $t'_{ijk} = 0$  unless  $i = j = k$ .

We have shown that

$$S' = (I - \Lambda)^T S (I - \Lambda), \quad T' = T \bullet (I - \Lambda) \bullet (I - \Lambda) \bullet (I - \Lambda)$$

are diagonal, and  $S'$  is positive definite since  $S$  is, which means that

$$S = (I - \Lambda)^{-T} S' (I - \Lambda)^{-1}, \quad T = T' \bullet (I - \Lambda)^{-1} \bullet (I - \Lambda)^{-1} \bullet (I - \Lambda)^{-1}$$

lie in our model. □

**Example 3.9.** Recall the graph in Example 3.4. Computations in `Macaulay2` show that  $\mathcal{I}^{(2,3)}(G) = I = (J : s_{11}^\infty)$ . In particular,  $\mathcal{M}^{(2,3)}(G) = V(I) \cap PD(5) = V(J) \cap PD(5)$ .

## 4 An application: trees with latent variables

In this section we apply our computational tools and theoretical findings to find the ideals of factor analysis models with latent (or hidden) variables.

**Definition 4.1.** Let  $H \cup O$  be a partition of the nodes of the DAG  $G$ . The hidden nodes  $H$  are said to be upstream from the observed nodes  $O$  in  $G$  if there are no edges  $o \leftarrow h$  in  $G$  with  $o \in O$  and  $h \in H$ .

**Example 4.2.** Recall the graph in Example 3.4. Consider the partition  $G = H \cup O$  with  $H = \{1\}$  and  $O = \{2, 3, 4, 5\}$ . Let  $I_O$  be the vanishing ideal of the model over the observed variables. `Macaulay2` computations show that  $I_O = I \cap \mathbb{C}[s_{ij}, t_{ijk} : i, j, k \in O] = K$ , where  $K$  is the ideal generated by the  $A_{i,j}$  matrices associated to  $G$  after removing all columns and rows containing variables with index 1. In particular, it is a binomial ideal minimally generated by 126 quadratic binomials.

The behavior displayed in Example 4.2 is known to be true for vanishing ideals of partially observed Gaussian models arising from trees [7, Section 6]. Assuming Conjecture 3.7 to be true, then  $I_O^{(2,3)}(G)$  for any DAG tree  $G$  is generated by the minors of the submatrices of  $A_{i,j}$  with  $i, j$  both in  $O$ , with columns indexed by  $k$  and  $l, m$  where  $k, l, m$  are all in  $O$ . In the rest of this section we explain how to prove this result.

For an upstream partition we define here a grading on the ring  $\mathbb{C}[a, b, \lambda]$ , which induces a grading on  $\mathbb{C}[s, t]$  such that the corresponding moment ideal is homogeneous. Let  $\deg a_h = (1, 1)$  for all  $h \in H$  and  $\deg a_o = (1, 3)$  for all  $o \in O$ . Similarly let  $\deg b_h = (1, 0)$  for all  $h \in H$  and  $\deg b_o = (1, 3)$  for all  $o \in O$ . Finally let  $\deg \lambda_{ho} = (0, 1)$  for all  $h \in H$  and  $o \in O$ , and  $\deg \lambda_{i,j} = (0, 0)$  otherwise.

**Lemma 4.3.** *For such an upstream partition, the above grading induces a grading on  $\mathbb{C}[s, t]$  with*

$$\deg s_{ij} = (1, 1 + \text{number of elements in the multiset } \{i, j\} \text{ in } O)$$

and

$$\deg t_{ijk} = (1, \text{number of elements in the multiset } \{i, j, k\} \text{ in } O).$$

Thus the ideal  $I^{(2,3)}(G)$  is homogeneous with respect to this grading.

Using this lemma and assuming Conjecture 3.7 to be correct, we can prove the claim because the only homogeneous polynomials of degree  $(n, 3n)$  in  $I^{(2,3)}$  must entirely consist of variables  $s_{i,j}, t_{i,j,k}$  with all indices  $i, j, k$  in  $O$ .

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