

Computing efficiently the non-properness set of polynomial maps on the plane

Joint work with Elias Tsigaridas

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Dominant polynomial maps and properness

Definition

Let \mathbb{k} be the field \mathbb{C} or \mathbb{R} . A map $f = (f_1, \dots, f_n) : \mathbb{k}^n \rightarrow \mathbb{k}^n$ is

- **dominant** if $|\text{Jac}_x f| \neq 0$ for some $x \in \mathbb{k}^n$, and
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Example

The map $(u, v) \mapsto (uv, v)$ is non-proper at $\{(r, s) \in \mathbb{k}^2 \mid s = 0\}$ since $f^{-1}(r, s) = (r/s, s)$.

The set of non-properness

$f : \mathbb{k}^n \rightarrow \mathbb{k}^n$ – dominant polynomial map, $\mathbb{k} \in \{\mathbb{C}, \mathbb{R}\}$.

Let \mathcal{J}_f denote the **non-properness set** of f , i.e.

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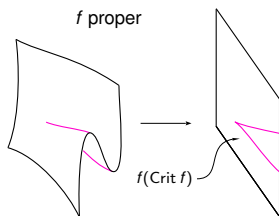
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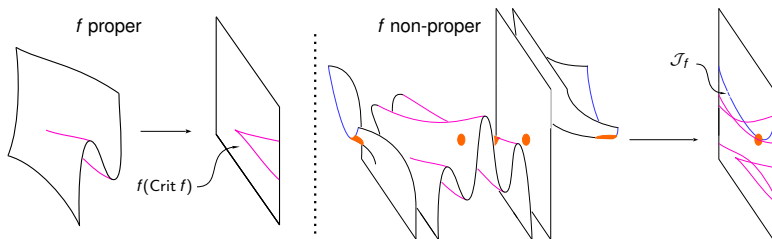
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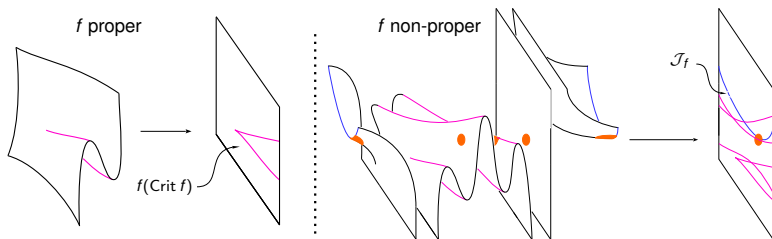
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Question

How to compute/approximate \mathcal{J}_f ?

Appearance in classical problems

- The **Jacobian conjecture** for polynomial maps $f : \mathbb{C}^n \rightarrow \mathbb{C}^n$:

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- Maps $F : X \rightarrow Y$ model problems in **multiview geometry** and **robotics**.

\mathcal{J}_F represents all inputs $y \in Y$ to which the solution $F^{-1}(y)$ is sub-optimal.

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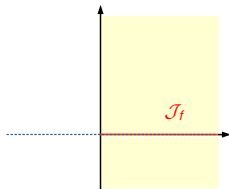
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Example

$$f : (u, v) \mapsto (u^2 v^2, v) \rightsquigarrow \mathcal{J}_f = \mathbb{R}_+ \times \{0\}$$



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and introduced methods from **elimination theory** to compute \mathcal{J}_f for $\mathbb{k} = \mathbb{C}$.
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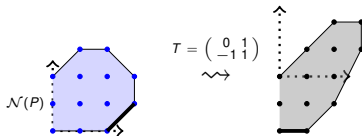
Problem

Design an efficient and complete method for computing \mathcal{J}_f .

Notations

P – bivariate polynomial $\sum_{w \in \mathbb{N}^2} c_w x^w$; $x^w = x_1^{w_1} x_2^{w_2}$.

$\mathcal{N}(P)$ – **Newton polytope** of P , i.e. convex hull in \mathbb{R}^2 of $\{w \in \mathbb{N}^2 \mid c_w \neq 0\}$



Definition

Let Γ be an **edge** of $\mathcal{N}(P)$. A change of variables $z = \tau(x)$ is called **toric** if

$$\begin{aligned} \tau : (\mathbb{k}^*)^2 &\rightarrow (\mathbb{k}^*)^2 \\ x &\mapsto (x^{T_1}, x^{T_2}) \end{aligned}$$

for some $T := (T_1, T_2) \in \text{SL}(2, \mathbb{Z})$. It is **Γ -toric** if additionally $T \cdot \Gamma$ is horizontal.

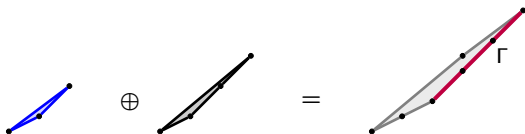
Pick the “smallest” $w \in \mathbb{N}^2$ such that $P_{\overline{\tau}}$ has non-negative exponents, where

$$P_{\overline{\tau}} := z^w P \circ \tau^{-1}$$

Γ -transformations for maps

$f = (f_1, f_2) : \mathbb{k}^2 \rightarrow \mathbb{k}^2$ – dominant polynomial map and y – generic point in \mathbb{k}^2

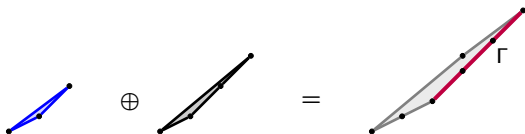
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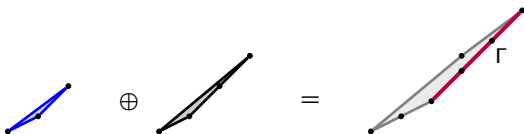
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$$(f - y)_{\bar{\tau}} := ((f_1 - y_1)_{\bar{\tau}}, (f_2 - y_2)_{\bar{\tau}})$$

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Example

Let $f - y$ be defined as the pair

$$(-y_1 + 2uv - u^2v^3, -y_2 + 12uv - 10u^2v^3 + 2u^3v^5)$$

and let Γ be the *purple* edge and $T = \begin{pmatrix} 1 & -1 \\ 2 & -1 \end{pmatrix}$. Then, $(f - y)_{\tau}$ is

$$(-y_1b + 2 - a, -y_2b + 12 - 10a + 2a^2)$$

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The Γ -multiplicity set of f , $\mathcal{M}_f(\Gamma)$, is the set of all points $\mathbf{y} \in \mathbb{k}^2$ such that for any $\mathbf{q} \rightarrow \mathbf{y}$, there exists a point $\mathbf{p} \in (\mathbb{k}^*)^2$ such that $\mathbf{p} \rightarrow \mathbf{q} \in \mathbb{k}^* \times \{0\}$, and

$$(f - \mathbf{q})_{\overline{\tau}}(\mathbf{p}) = 0.$$

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$f = (f_1, f_2) : \mathbb{k}^2 \rightarrow \mathbb{k}^2$ – dominant polynomial map
 Γ – edge of $\mathcal{N}(f)$ and τ – Γ -toric change of variables

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Example

Consider the pair $(f - \mathbf{y})_{\overline{\tau}}(a, b)$ from before:

$$(2 - a - y_1 b, 12 - 10a + 2a^2 - y_2 b).$$

The system $(f - \mathbf{y})_{\overline{\tau}} = 0$ has solutions $(2, 0)$ and $(\frac{6y_1 - y_2}{2y_1}, \frac{y_2 - 2y_1}{2y_1^2})$. We have

$$|\text{Jac}(f - \mathbf{y})_{\overline{\tau}}|_{|(2,0)} = y_2 - 2y_1.$$

The Γ -multiplicity set $\mathcal{M}_f(\Gamma)$ is given by

$$\{\mathbf{y} \in \mathbb{k}^2 \mid y_2 - 2y_1 = 0\}.$$

Main result

Theorem (EH, Tsigaridas, 2020)

Let \mathbb{k} be the field \mathbb{C} or \mathbb{R} and let $f : \mathbb{k}^2 \rightarrow \mathbb{k}^2$ be a dominant polynomial map. Then, for some choices of Γ -toric change of variables, we have

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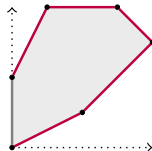
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Input $f_1, f_2 \in \mathbb{k}[x_1, x_2], \mathbb{k} \in \{\mathbb{C}, \mathbb{R}\}$

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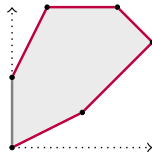
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Design an algorithm to compute $\mathcal{M}_f(\Gamma)$.

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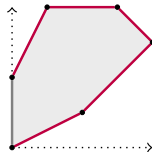
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Remark: Points $y \in \mathcal{M}_f(\Gamma)$ change the multiplicities of solutions in $\mathbb{k}^* \times \{0\}$ to

$$(f - y)_{\overline{\Gamma}} = 0$$

Computing multiplicities for bivariate systems

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Then, we have

$$\mathcal{M}_f(\Gamma) \subset \text{Mult}_f(\Gamma)$$

Our contribution

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A method and an algorithm that computes \mathcal{J}_f :

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Flexible: Can be optimized and refined to some applications

Thank you!

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