

# Inferring Polynomial Relationships from Partial Data Using Matrix Rank Minimization

Christopher Gadzinski, me@cgad.ski

University of Coimbra

## Low Rank Matrix Completion and Company

Suppose  $M = [\mathbf{x}_1, \dots, \mathbf{x}_n]$  is a matrix of datapoints, some of whose coordinates are unknown.

$$M = \begin{bmatrix} m_{1,1} & m_{1,2} & ? & m_{1,4} & m_{1,5} & \dots \\ ? & m_{2,2} & ? & m_{2,4} & ? & \dots \\ m_{3,1} & ? & m_{3,3} & m_{3,4} & ? & \dots \\ ? & m_{4,2} & m_{4,3} & ? & m_{4,5} & \dots \end{bmatrix}$$

How can we infer latent relationships in this kind of **partially observed** data? This problem has applications in the design of *recommender systems*. For example: how can we infer patterns in the way that users rate movies when we have a small set of reviews from each user?

If our data is expected to be low-rank, it's natural to recover  $M$  as the matrix of *minimal rank* that agrees with the observed entries. This is the problem of **low rank matrix completion** (LRMC):

LRMC:

$$\begin{aligned} & \text{minimize} && \text{rank } M \\ & \text{subject to} && m_{i,j} = c_{i,j}, (i,j) \in \Omega \end{aligned}$$

The problem is essentially to determine the column space  $V$  of  $M$  from the information that  $V$  incides in certain affine subspaces. We call this a **hitting subspace problem**. Conversely, a general hitting subspace problem can be posed as a matrix rank minimization problem if we allow arbitrary affine constraints on each column. We call this **column-affine rank minimization** (CARM). This pair of equivalent problems generalizes the classic notion of LRMC.

Hitting subspace problem:

$$\begin{aligned} & \text{minimize} && \dim V \\ & \text{subject to} && V \cap W_i \neq \emptyset, i = 1 \dots n \end{aligned}$$

CARM:

$$\begin{aligned} & \text{minimize} && \text{rank}([\mathbf{x}_1, \dots, \mathbf{x}_n]) \\ & \text{subject to} && \pi_i(\mathbf{x}_i) = \tilde{\mathbf{x}}_i, i = 1 \dots n \end{aligned}$$

In [2], Candès and Recht showed that LRMC is often formally equivalent to a certain semidefinite program. This observation leads to some practical algorithms for LRMC, like the singular value thresholding algorithm (SVT) from [1]. In turn, SVT can be easily generalized to solve the more general CARM problem.

## How Much Data is Enough?

When is CARM well-posed, information-theoretically? There are two perspectives to consider:

**Are enough degrees of freedom cut?** When the  $r$ -dimensional column space of  $M$  is fixed, each additional column contributes an additional  $r$  degrees of freedom, so, a new column with  $k > r$  affine constraints should impose  $k - r$  extra constraints on  $V$ . Naively, we expect that completion of a rank  $r$  matrix should be possible when at least

$$\left\lceil \frac{r(m-r)}{k-r} \right\rceil$$

datapoints are given with  $k$  observed coordinates each.

**Is  $V$  identifiable from the projections  $\pi_i$ ?** Suppose we observe arbitrarily many datapoints under each projection  $\pi_1, \dots, \pi_l$ . Generally, the most we can learn about  $V$  is summarized by the images  $\pi_i(V)$ . In fact, for generic subspaces  $V$ , LRMC will succeed on a sufficiently large dataset projected under the maps  $\pi_i$  if and only if

$$V = \bigcap_i \pi_i^{-1}(\pi_i(V)).$$

In this case, we say that  $V$  is *identifiable* under the projections  $\pi_i$ .

## LRMC in Polynomial Feature Space

What if our data is drawn from a nonlinear *algebraic variety*? Can we generalize LRMC to exploit higher degree polynomial relationships?

Let  $v: \mathbb{R}^m \rightarrow (\mathbb{R}^m)^{\otimes p}$  be the Veronese map, sending a point  $x$  to its  $p$ -fold symmetric tensor power. If the columns  $\mathbf{x}_i$  of  $M = [\mathbf{x}_1, \dots, \mathbf{x}_n]$  are drawn from a variety  $\mathcal{V}$  that is cut out by degree- $p$  polynomials, then the matrix  $v(M) = [v(\mathbf{x}_1), \dots, v(\mathbf{x}_n)]$  will be rank-deficient. So, the natural way to infer  $M$  from the column-wise affine constraints  $\pi_i(\mathbf{x}_i) = \tilde{\mathbf{x}}_i$  is to solve the following "lifted" version of LRMC.

Nonlinear LRMC:

$$\begin{aligned} & \text{minimize} && \text{rank}[v(\mathbf{x}_1), \dots, v(\mathbf{x}_n)] \\ & \text{subject to} && \pi_i(\mathbf{x}_i) = \tilde{\mathbf{x}}_i, i = 1 \dots n. \end{aligned}$$

However, *affine* constraints on the columns of  $M$  give rise to implicit *nonlinear* constraints on the columns of  $v(M)$ . **How can we solve this new class of rank minimization problems?** In [3], Ongie et al. suggested that  $v(M)$  could be inferred (in some cases) **as a solution to a LRMC problem**. In our work, we suggest an improved way to infer it **as a solution to a hitting subspace problem**.

Given a coordinate projection  $\pi: \mathbb{R}^m \rightarrow \mathbb{R}^k$  onto a subset  $S$  of coordinates, let  $\pi^{\otimes p}$  denote the naturally associated map from  $(\mathbb{R}^m)^{\otimes p}$  to  $(\mathbb{R}^k)^{\otimes p}$  that projects onto the coordinates corresponding to monomials supported on  $S$ . When  $v: \mathbb{R}^k \rightarrow (\mathbb{R}^k)^{\otimes p}$  is the Veronese map for  $\mathbb{R}^k$ ,  $\pi^{\otimes p}$  makes the following diagram commute.

$$\begin{array}{ccc} \mathbb{R}^m & \xrightarrow{v} & (\mathbb{R}^m)^{\otimes p} \\ \downarrow \pi & & \downarrow \pi^{\otimes p} \\ \mathbb{R}^k & \xrightarrow{v} & (\mathbb{R}^k)^{\otimes p} \end{array}$$

If  $\pi(\mathbf{x}) = \tilde{\mathbf{x}}$ , then  $\pi^{\otimes p}(v(\mathbf{x})) = v(\pi(\mathbf{x})) = v(\tilde{\mathbf{x}})$ , so  $\pi^{\otimes p}(\mathbf{y}) = v(\tilde{\mathbf{x}})$  is a relaxation of the constraint that  $\mathbf{y} \in v(\pi^{-1}(\tilde{\mathbf{x}}))$ . On the other hand, a stronger condition is to stipulate that  $\mathbf{y}$  should lie in the linear span of  $v(\pi^{-1}(\tilde{\mathbf{x}}))$ . These two approaches give the following rank-minimization problems for  $v(M)$ .

Tensorized LRMC:

$$\begin{aligned} & \text{minimize} && \text{rank}[\mathbf{y}_1, \dots, \mathbf{y}_n] \\ & \text{subject to} && \mathbf{y}_i \in (\mathbb{R}^m)^{\otimes p}, \\ & && \pi_i^{\otimes p}(\mathbf{y}_i) = v(\tilde{\mathbf{x}}_i), i = 1 \dots n \end{aligned}$$

Tensorized hitting subspace problem:

$$\begin{aligned} & \text{minimize} && \text{rank}[\mathbf{y}_1, \dots, \mathbf{y}_n] \\ & \text{subject to} && \mathbf{y} \in \langle v(\pi_i^{-1}(\tilde{\mathbf{x}}_i)) \rangle \setminus 0, i = 1 \dots n \end{aligned}$$

Ongie et al. showed that *tensorized LRMC* is well-posed on sufficiently large datasets drawn from certain *unions of subspaces*. However, our new *tensorized hitting subspace problem* may let us recover  $v(M)$  more frequently, because it imposes more constraints on each column of  $v(M)$ .

Consider the case  $p = 2$ . Let  $\mathbf{x} = (x_1, \dots, x_m)$  be a column of  $M$ , and suppose the coordinates  $x_1, \dots, x_k$  are known. What constraints can we impose on the corresponding column of  $v(M)$ ,

$$\mathbf{y} = v(x) = (y_{i,j})_{1 \leq i \leq j \leq n} = (x_i x_j)_{1 \leq i \leq j \leq n}?$$

In the LRMC approach, we simply use the  $\binom{k+1}{2}$  equations  $y_{i,j} = x_i x_j$  for  $1 \leq i \leq j \leq k$ . However, the tensorized hitting subspace problem leads us to consider, e.g., the  $(k-1)(m-k)$  new equations

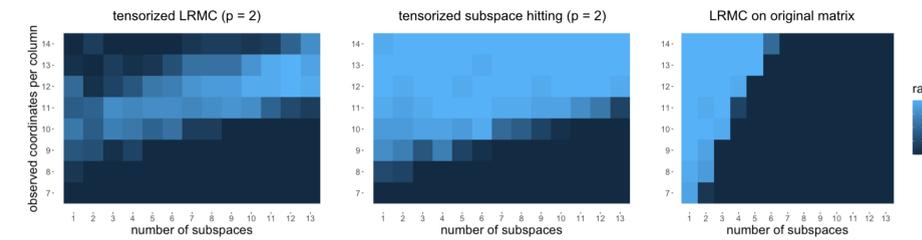
$$y_{1,i} = \frac{x_1}{x_j} y_{j,i}$$

for  $k < i \leq n$  and  $2 \leq j \leq k$ . Especially when  $k \ll m$ , this is a big improvement!

## An Experiment on Unions of Subspaces

Choose  $K$  2-dimensional subspaces  $S_1, \dots, S_K$  in  $\mathbb{R}^{15}$ . Generate a dataset of  $50K$  points, with 50 points drawn from each subspace. Permute the dataset so that the clusters of points drawn from each subspace are unknown, and retain only  $m$  coordinates from each datapoint. **Can we recover the missing coordinates?**

We compare the performance of regular LRMC against algorithms derived from the tensorized LRMC problem and the tensorized hitting subspace problem. For a given value of  $K$  and  $m$ , we solve 20 pseudorandom problem instances and report the fraction of times that our process imputes the missing coordinates of the original matrix to within a modest tolerance. For the LRMC / CARM subproblems, we use naive implementation of singular value thresholding, limited to 200 iterations.



When  $K > 7$ , the matrix  $M$  we are completing is no longer rank-deficient, so applying LRMC to the original matrix completion problem cannot possibly succeed. Meanwhile, as already noted by Ongie et al., lifting the problem into the tensorized domain does let us impute  $M$  in this high-rank situation. We extend on this observation: at least with the rank-minimization algorithm we have used, using the *tensorized hitting subspace problem* lets us impute  $M$  even more reliably.

## Future Directions

It can be shown that the success of tensorized LRMC is contingent on some special properties of the data. Specifically, if no more than  $k$  coordinates of each data point are observed, Ongie's method will not succeed at completing data drawn from an algebraic variety  $\mathcal{V}$  unless the space of  $p$ th degree homogeneous polynomials in the vanishing ideal of  $\mathcal{V}$  is generated by polynomials supported on no more than  $k$  coordinates. However, while degree-of-freedom reasoning suggests that the tensorized hitting subspace problem will recover  $v(\mathcal{V})$  in more situations, little is currently known about its precise limitations.

## References and Acknowledgements

- [1] Jian-Feng Cai, Emmanuel J. Candès, and Zuowei Shen. A singular value thresholding algorithm for matrix completion, 2008.
- [2] Emmanuel J. Candès and Benjamin Recht. Exact matrix completion via convex optimization, 2008.
- [3] Greg Ongie, Daniel Pimentel-Alarcón, Laura Balzano, Rebecca Willett, and Robert D. Nowak. Tensor methods for nonlinear matrix completion, 2020.

The work presented in this paper was partially carried out in the scope of the *MobiWise* project: From mobile sensing to mobility advising (P2020 SAICTPAC/0011/2015), co-financed by COMPETE 2020, Portugal 2020 - Operational Program for Competitiveness and Internationalization (POCI), European Union's ERDF (European Regional Development Fund), and the Portuguese Foundation for Science and Technology (FCT).

